

# The BTeV Trigger and $B^0 \rightarrow \pi^+\pi^-$

Erik Gottschalk

Fermilab



Tevatron B Physics  
Workshop  
February 24, 2000

# Overview

---

After submitting a preliminary technical design report (PTDR) in May 1999, the BTeV collaboration has been working to simplify the design of the spectrometer and to reduce the amount of material in the detector.

A substantial part of the material is in the BTeV pixel system. By eliminating a total of 31 pixel planes and by simplifying the design of the pixel system, we now have a new design that has **60%** of the material of the PTDR design.

- the new pixel system is easier to build
- fewer photon conversions and reinteractions in the pixel system
- less cooling required for the new system
- lower cost
- $\frac{2}{3}$  the number of pixels (less data per event)

... but what about the Level 1 trigger?



## Overview (cont.)

---

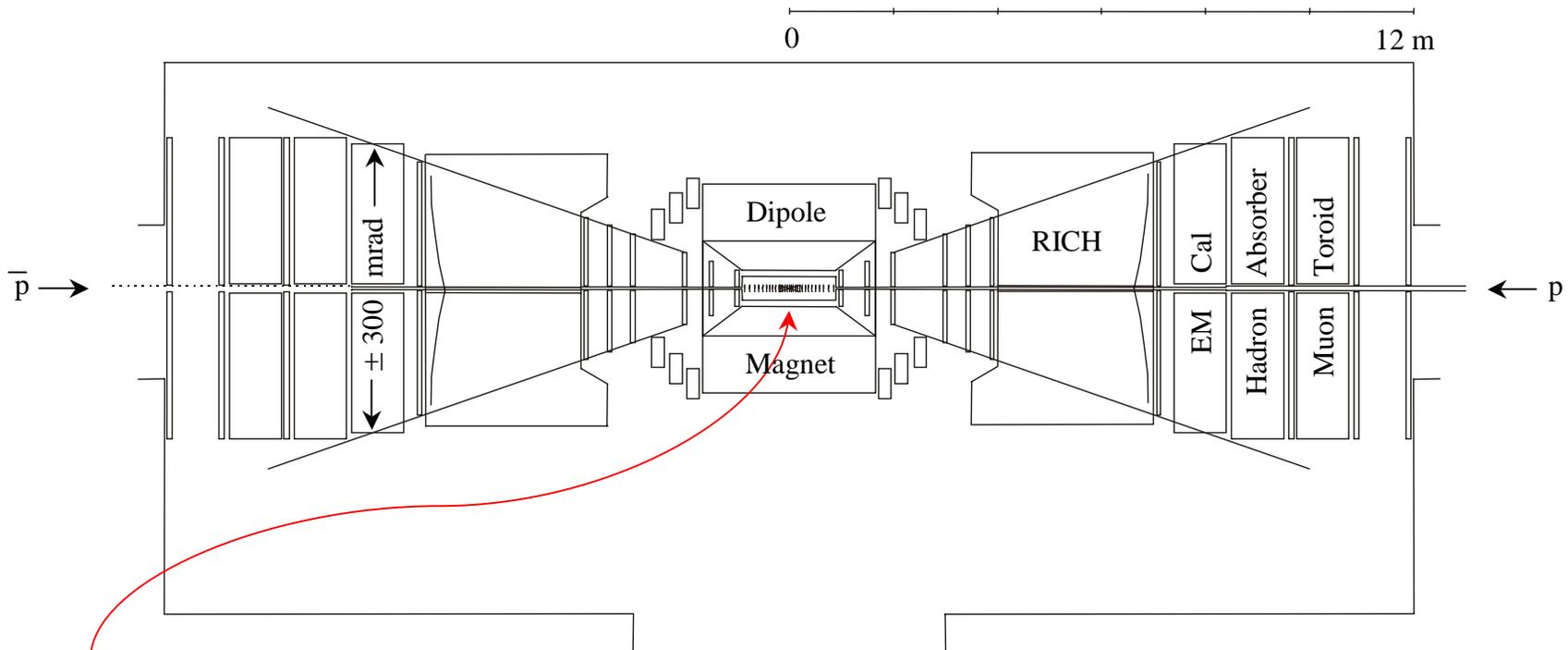
The Level 1 vertex and impact parameter trigger is a key component of BTeV.

Events with  $B$  decays are found by using data from the pixel detector to reconstruct primary vertices, so that  $B$ -decay tracks can be identified using an impact parameter calculation. This analysis is performed by the Level 1 trigger for every beam crossing.

- the Level 1 trigger makes BTeV especially efficient for  $B$ 's decaying into hadrons
  - the trigger design is tied closely to the design of the pixel tracking system
  - physics analyses depend on the design of the Level 1 trigger, since the trigger represents the first step of the data analysis (especially for hadronic  $B$  decays)
- 
- New geometry for the BTeV pixel detector (2 instead of 3 planes per tracking station)
  - New baseline design for the Level 1 trigger
  - Updated PTDR results for  $B^0 \rightarrow \pi^+\pi^-$  physics simulations



# Plan View of the BTeV Detector



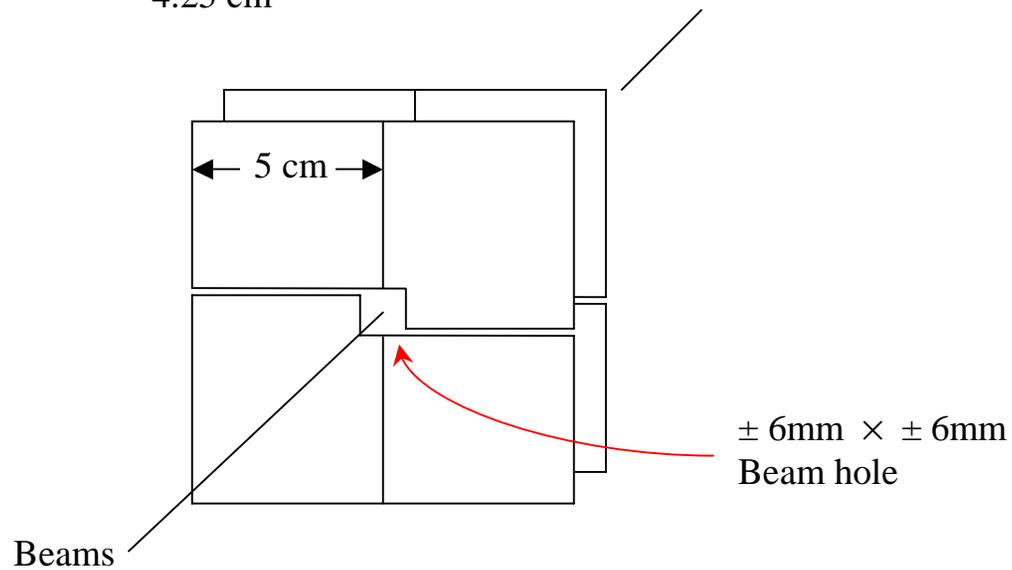
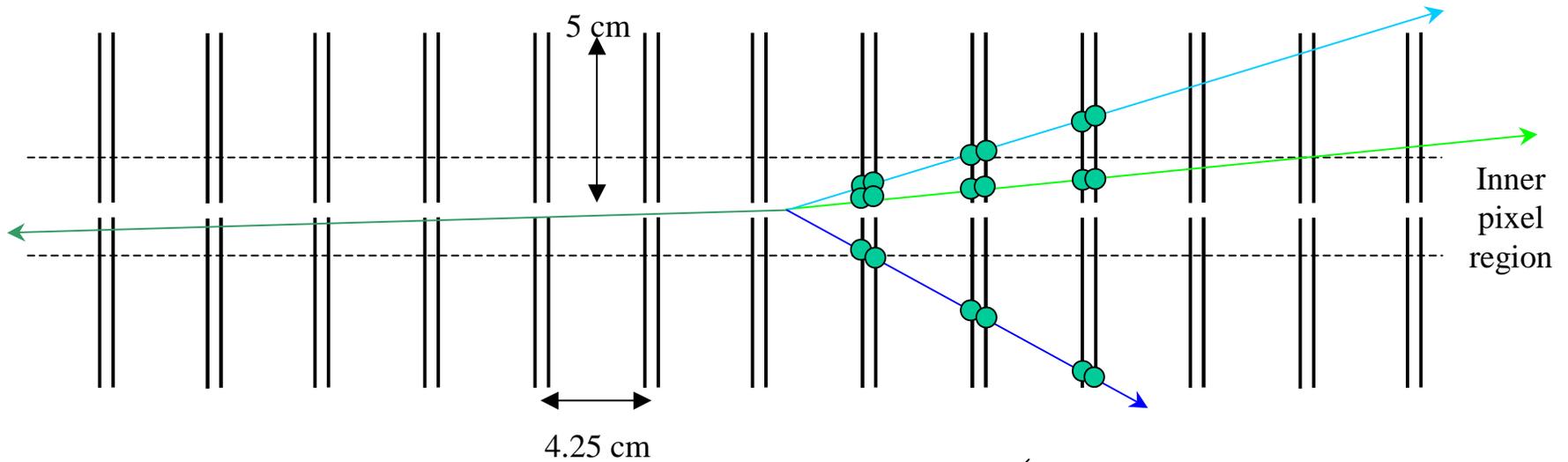
## Pixel System (inside beam vacuum):

- 31 stations distributed over 128 cm ( $\pm 64$  cm)
- Each station has 2 planes arranged in “views” (y,x)
- Each plane has over 500,000 pixels in a 10 x 10 cm area (square beam hole)
- Each pixel is 50 x 400  $\mu$  in size (pulse height measurement for each pixel)

**NEW geometry!**



# Close-up View of the Pixel System



# Overview of the Level 1 Trigger

---

The Level 1 trigger performs 4 analysis steps:

- pattern recognition using pixel hits
- track reconstruction and extrapolation to the beam region
- primary vertex reconstruction and impact parameter calculation
- trigger decision based on the number of tracks with large impact parameter

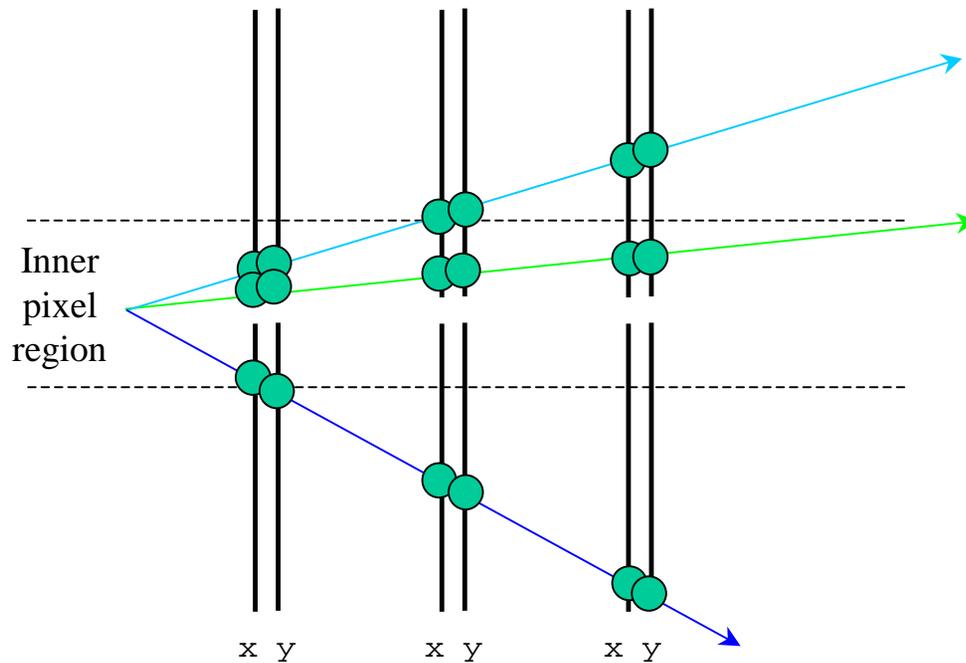
Key features of our NEW baseline trigger:

- find tracks as they **enter** the pixel detector (tracks are called **interior triplets**)
- find tracks as they **exit** the pixel detector (tracks are called **exterior triplets**)
- the first hit on a track is required to be within the “inner pixel region”
- the last hit is required to be in the “outer pixel region”
- simple and draconian removal of fake tracks (kill tracks that share hits)



# Pattern Recognition in the Level 1 Trigger

---



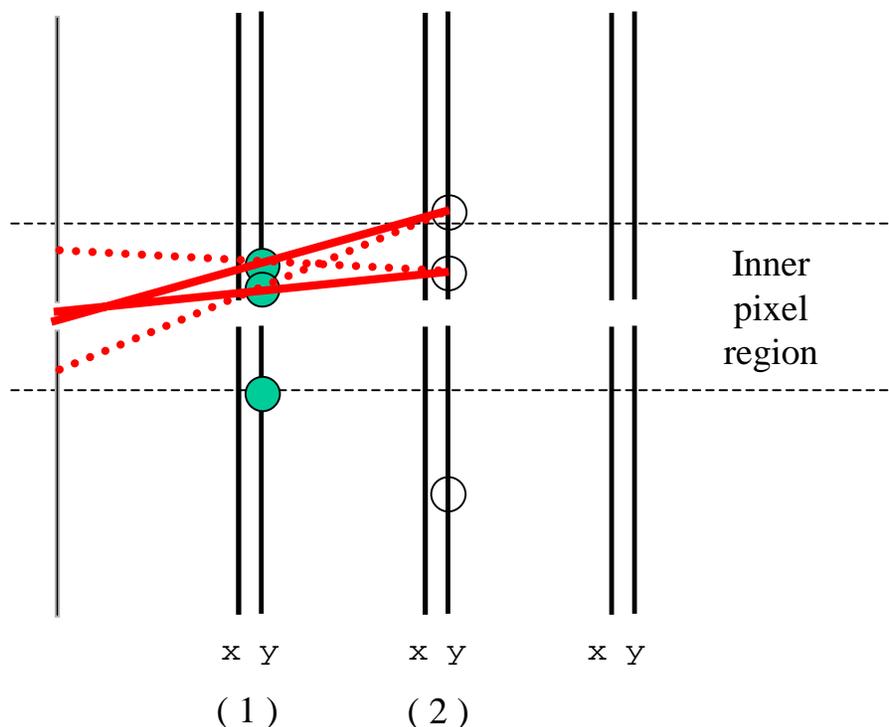
The pixel hits from three stations are sent to an FPGA tracker, for pattern recognition:

- interior and exterior track **doublet finder** (precision  $y$  hits)
- interior and exterior track **triplet finder** (precision  $y$  hits)
- interior  $x$ -hit matcher (requires 2 of 3 matching  $x$  hits)

Interior and exterior triplets are sent to a farm of digital signal processors to complete the pattern recognition:

- interior/exterior triplet matcher
- fake-track removal

# Find interior “doublets” using precision y hits in pixel stations 1 & 2



The goal is to find the first two hits on a track:

- doublet finder considers pairs of hits from stations 1 and 2
- the hit in station 1 is required to be within a 3 cm x 3 cm region (inner pixel region) to reduce the number of doublets, and still be more than 99% efficient for finding tracks
- project to “upstream” station by calculating
 
$$x = 2 * x_1 - x_2$$

$$y = 2 * y_1 - y_2$$
- require that the calculated position (x,y) falls within the 1.2 cm x 1.2 cm beam region

Fortran:

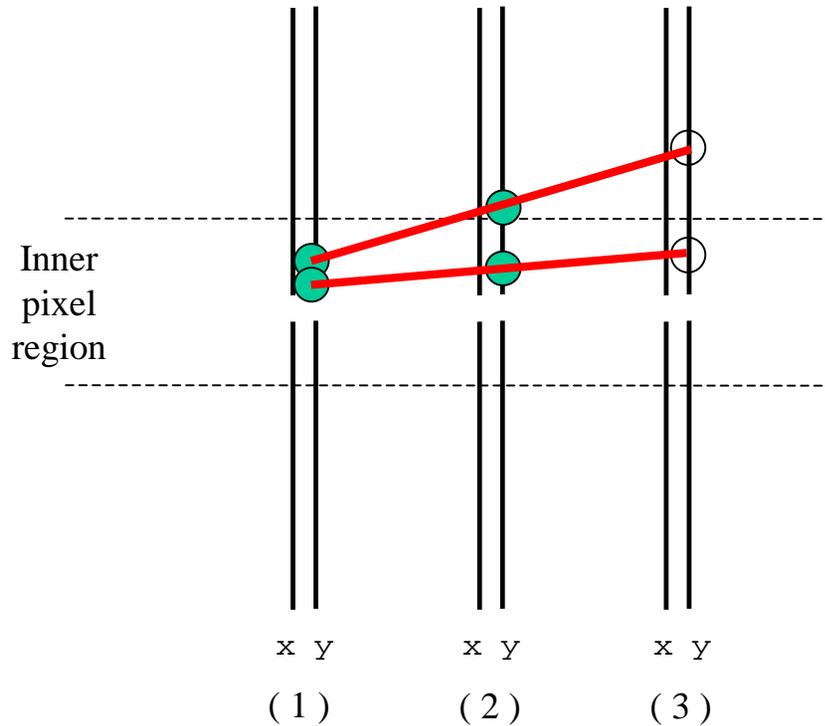
```
abs ( 2 * x1 - x2 ) .LT. 0.6
abs ( 2 * y1 - y2 ) .LT. 0.6
```

Associative Memory:

```
x2 < ( 2 * x1 - 0.6) AND x2 > ( 2 * x1 + 0.6)
y2 < ( 2 * y1 - 0.6) AND y2 > ( 2 * y1 + 0.6)
```



# Find “triplets” using the doublets and precision y hits in station 3



Find the first three hits on a track:

- triplet finder looks for a confirming third hit in a 2mm x 1mm window in station 3 for each doublet found by the doublet finder

- the confirming third hit reduces the number of fake tracks found by the doublet finder

- project to “downstream” station by calculating

$$x = 2 * x_2 - x_1$$

$$y = 2 * y_2 - y_1$$

- hits that fall in the 2mm x 1mm window centered on the projected position produce a triplet, and the change in y slope ( $\Delta m = m_{23} - m_{12}$ ) is used at a later stage to find matching **exterior** triplets

Fortran:

```
abs (x3 - ( 2 * x2 - x1 )) .LT. 0.1
abs (y3 - ( 2 * y2 - y1 )) .LT. 0.05
```

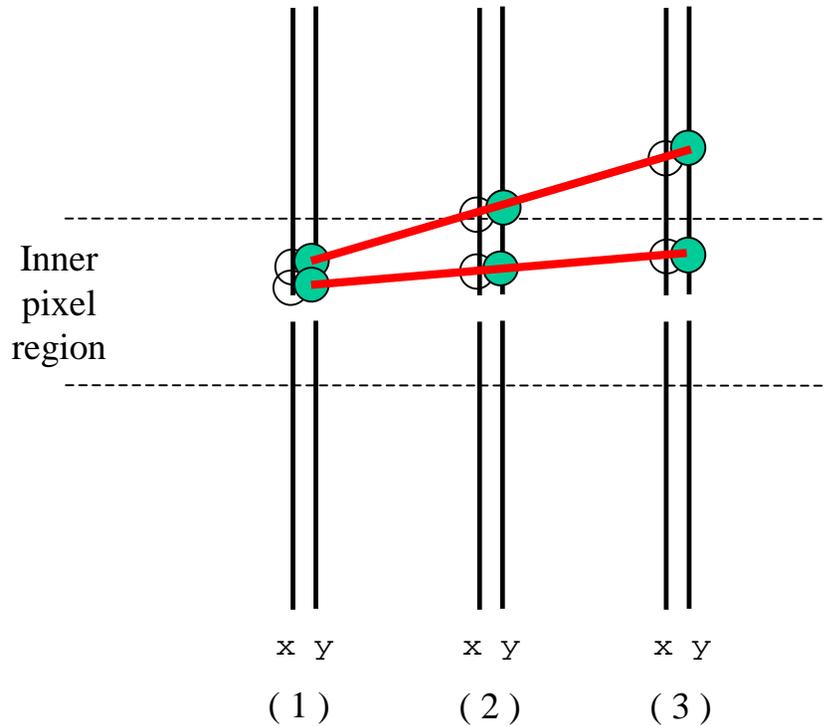
Associative Memory:

```
x3 < (2 * x2 - x1) - 0.10 AND x3 > (2 * x2 - x1) + 0.10
y3 < (2 * y2 - y1) - 0.05 AND y3 > (2 * y2 - y1) + 0.05
```



# Find matching x hits for interior triplets for stations 1, 2 & 3

---

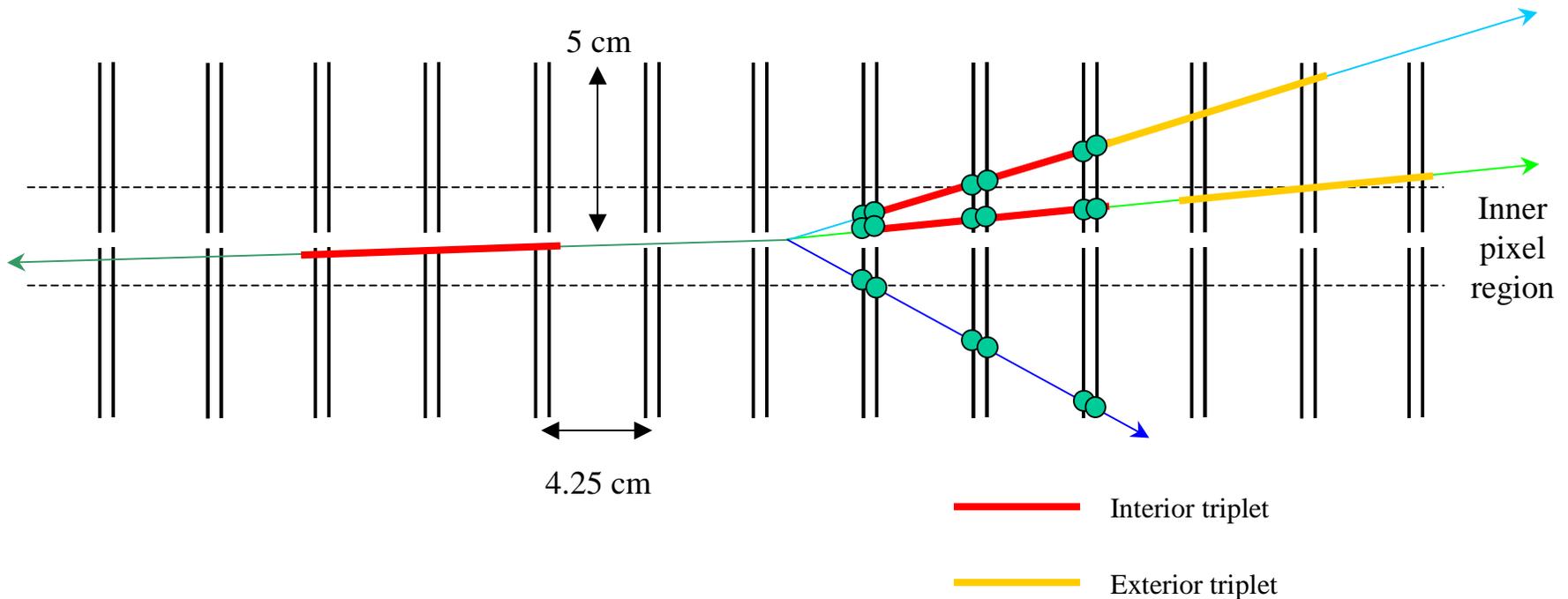


- x-hit matcher uses the track slope to find hits in a window ( $800\mu \times 1200\mu$ ) in precision x planes for interior triplets only
- tracks are required to have 2 out of 3 matching hits
- x hits are used to find matching **exterior** triplets



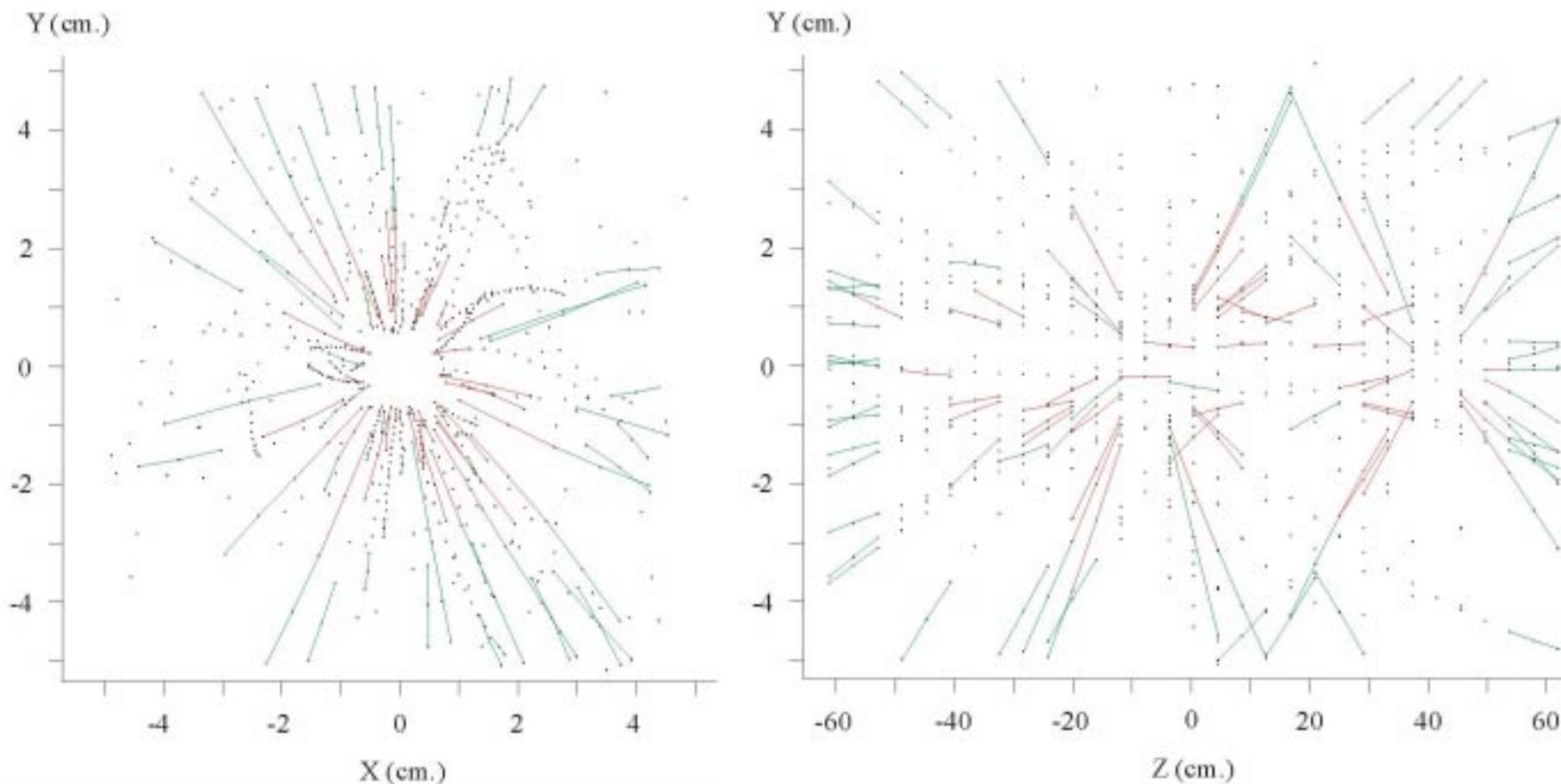
# Find matching exterior triplets for each interior triplet

---



- interior/exterior matcher links interior and exterior triplets
- current algorithm has a 2% loss in tracking efficiency (not understood)

# Pattern Recognition for “y-hits” in a Generic $B$ Event



— Interior triplet

— Exterior triplet



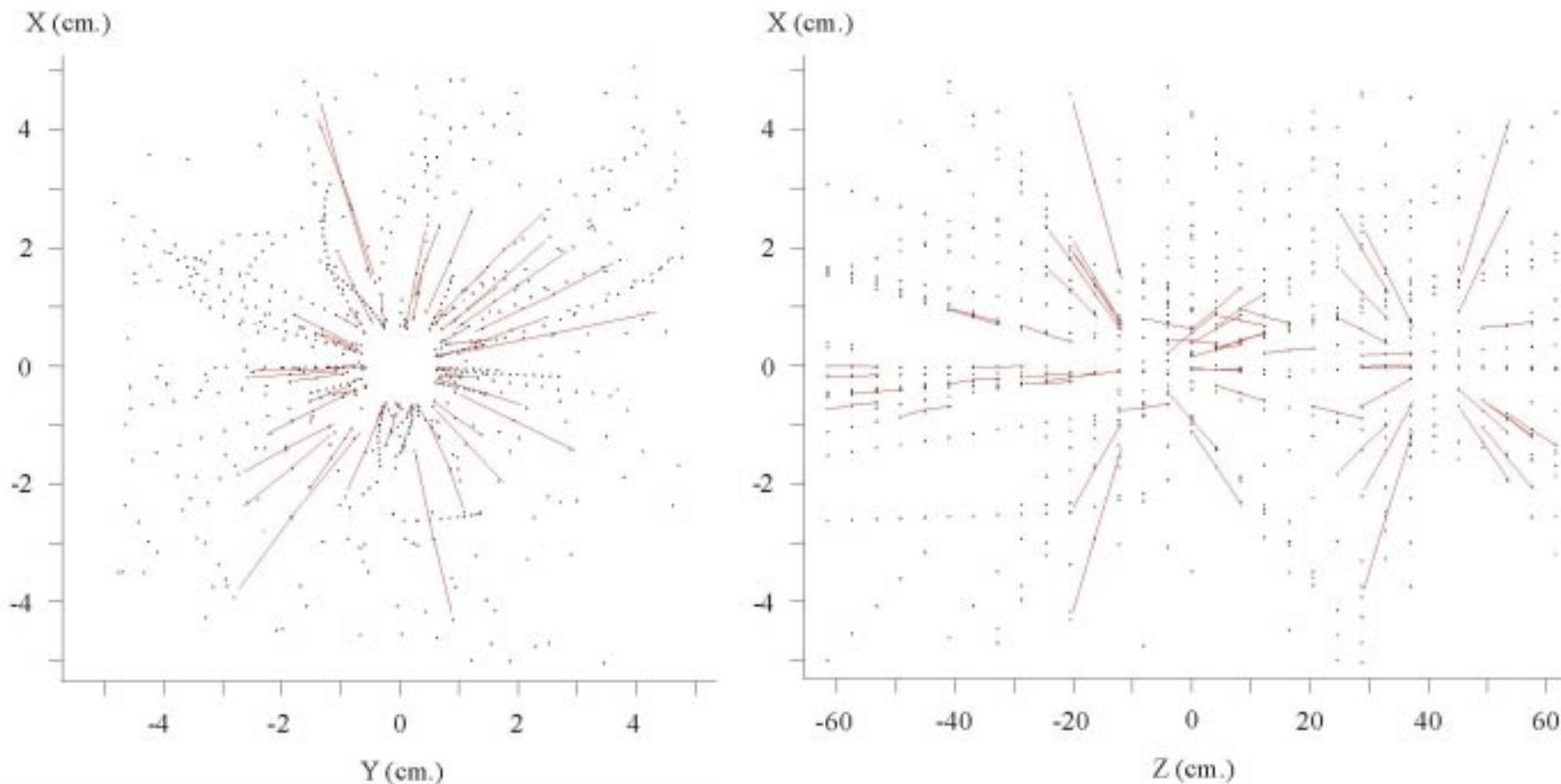
The BTeV Trigger and  $B^0 \rightarrow \pi^+\pi^-$

Erik Gottschalk



# Precision x-hits used by the Level 1 Trigger

---



— Interior triplet

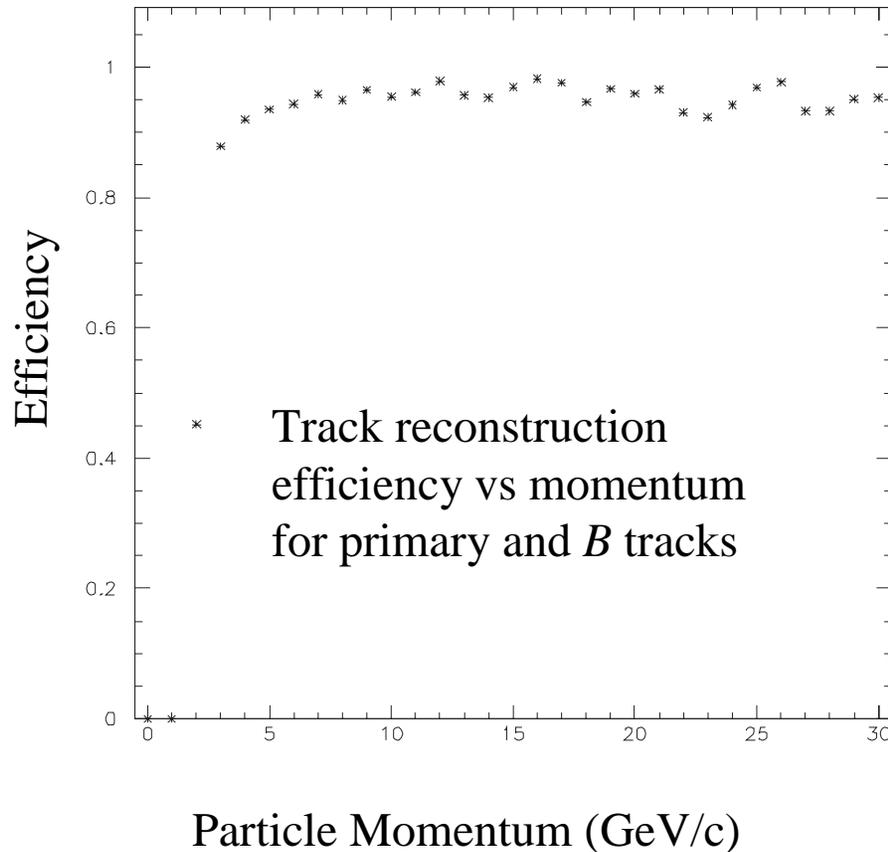


The BTeV Trigger and  $B^0 \rightarrow \pi^+\pi^-$

Erik Gottschalk



# Track Reconstruction Efficiency (for primary and $B$ tracks)



Trigger Algorithm	Track Reconstruction Efficiency ( $p > 5$ GeV)	
<b>Track doublet finder (precision y hits)</b>	Interior 99.5%	Exterior 99.8%
<b>Track triplet finder (precision y hits)</b>	Interior 99.4%	Exterior 99.6%
<b>Hit matcher (precision x hits)</b>	Interior 99.4%	
<b>Int./Ext. matcher</b>	95.9%	
<b>Fake removal</b>	95.3%	



# Fake Tracks at each Stage of the Level 1 Pattern Recognition

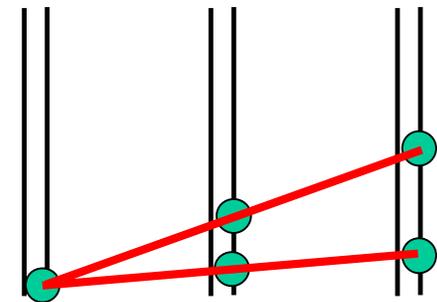
Trigger Algorithm	Percentage of Tracks that are fake	
<b>Track doublet finder (precision y hits)</b>	Interior 81.4%	Exterior 78.1%
<b>Track triplet finder (precision y hits)</b>	Interior 16.5%	Exterior 8.6%
<b>Hit matcher (precision x hits)</b>	Interior 14.5%	
<b>Int./Ext. matcher</b>	1.5%	
<b>Fake removal</b>	0.71%	

Of the fake tracks that remain:

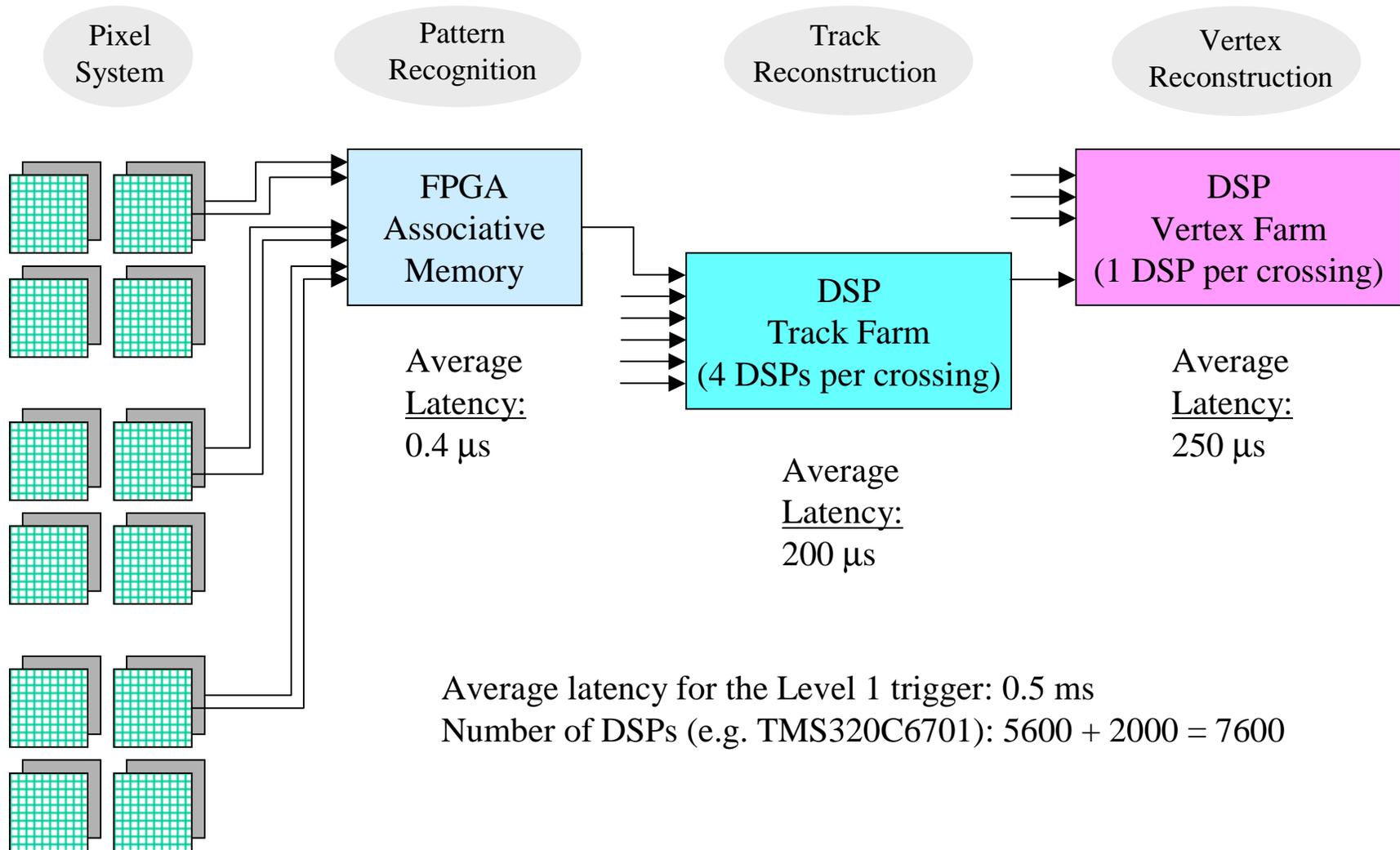
- 53% have fake interiors
- 47% have fake exteriors

Note:

The last stage of the Level 1 pattern recognition removes fake tracks by removing all tracks that share hits with other tracks.



# Block Diagram of the Level 1 Trigger



# Status of the Level 1 Trigger

---

New trigger results (2 interactions per beam crossing):

- 75% trigger efficiency for  $B_s \rightarrow D_s K$  (the PTDR value is 70%)
- 62% trigger efficiency for  $B^0 \rightarrow K \pi$  (the PTDR value is 54%)
- 1% of minimum bias (light quark) events produce a trigger
- good performance with “noise” hits exceeding  $10^{-4}$
- good performance with pixel efficiencies down to 98%
- hardware architecture that can be built with today’s technology

Note: the trigger efficiency for  $B^0 \rightarrow \pi \pi$  should be around 60%



# Updated PTDR Results for $B^0 \rightarrow \pi^+ \pi^-$

Parameter	PTDR Value	New Value
Luminosity	$2 \times 10^{32} \text{ cm}^{-2} \text{ s}^{-1}$	$2 \times 10^{32} \text{ cm}^{-2} \text{ s}^{-1}$
$B$ cross section	100 $\mu\text{b}$	100 $\mu\text{b}$
$B$ events per $10^7$ seconds	$2 \times 10^{11}$	$2 \times 10^{11}$
Number of $B_d$ 's	$1.4 \times 10^{11}$	$1.4 \times 10^{11}$
$B_d \rightarrow \pi^+ \pi^-$ branching fraction	$0.75 \times 10^{-5}$	<b><math>0.43 \times 10^{-5}</math></b>
Reconstruction efficiency	0.06	0.06
Trigger efficiency	0.55	<b>0.60</b>
Reconstructed $B_d \rightarrow \pi^+ \pi^-$	$3.4 \times 10^4$	<b><math>2.2 \times 10^4</math></b>
Tagging efficiency $\epsilon D^2$	0.10	0.10
S/B	0.6	0.6
$\delta a_{CP}$	0.023	<b>0.023</b>

Include factor from the  
time-dependent analysis



# Conclusions

---

BTeV has a new design for the pixel system:

- significantly LESS material (60% of the material compared to the PTDR)
- new system is easier to build, requires less cooling, lower cost
- reduces the number of photon conversions and reinteractions

BTeV has a new design for the Level 1 trigger

- better performance compared to the PTDR trigger
- the hardware architecture can be implemented using today's technology
- we anticipate further improvements in the design for the BTeV Proposal

We expect improvements in all physics simulations compared to the results we presented in the PTDR.

---

